



CLARREO Reflected Solar Spectrometer: Reference Inter-Calibration Activities

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Presentation Outline

1. Update on CLARREO RS Inter-calibration:

- **Paper on the Radiometric Uncertainty due to Polarization (TGRS).**
- **Paper on CLARREO RS sampling from the ISS.**
- **Current and planned studies and papers.**

2. Update on the Ground-to-Space Laser Calibration (GSLC) approach:

- **The GSLC concept at conclusion of LaRC SIF project (September 2012).**
- **Roadmap forward.**

Update on CLARREO RS Inter-calibration

1. Submitted & revised papers:

- **C. Roithmayr et al., “Opportunities to Intercalibrate Radiometric Sensors from International Space Station”, to be published at J. of the Astronautical Sciences (consistent with B. Dunn’s CLARREO/ISS concept).**
- **C. Lukashin et al., “Uncertainty Estimates for Imager Reference Inter-calibration with CLARREO Reflected Solar Spectrometer”, TGRS Special issue, revised manuscript is re-submitted. Editor Comments (quote):**
“An excellent paper on a challenging topic (CL - polarization) with major implications to the EO community particularly for climate quality observations.”

2. Current and planned papers and studies:

- **Finish paper on the CLARREO RS Inter-calibration sampling from P90 orbit.**
- **Write paper on the CLARREO RS requirement for sensitivity to polarization.**
- **Validation of CERES-derived surface BRDF over Dome-C using SCIAMACHY observations and RT modeling (S. Kato, C. Lukashin, A. Radkevich).**
- **Implementation of CLARREO RS inter-calibration algorithms into the MIIC (C. Currey, C. Lukashin, D. Doelling, and C. Roithmayr).**
- **Long term: Build empirical PDM database as a product or plug-in into MIIC.**



Ground-to-Space Laser Calibration (GSLC): Feasibility Study

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1 - NASA LaRC, Hampton, VA; 2 - Vigyan, Hampton, VA; 3 - SSAI, Hampton, VA

What is GSLC ?

- ◆ **The GSLC is an accurate **ground-to-space laser calibration** system, with **CW tunable laser**, 3 W transmit power, expanded beam with top-hat profile, 100% linear polarization.**
- ◆ **Transmitting laser light to instrument on orbit during **nighttime clear-sky** conditions, from a mountain top. Tracking the S/C in LEO and GEO.**
- ◆ **To minimize atmospheric contribution to the calibration uncertainty the calibration cycles should be performed in short time periods - a few seconds.**
- ◆ **All measurements are designed to be **relative**.**
- ◆ **The short-timed calibration cycles involve ground operations with laser beam – changing its **polarization** and **wavelength**.**



1. Motivation: Improvement in the EOS data products

1.1 RS Instrument Calibration Function includes (not limited to):

- Offset (temperature dependence);
- Offset & gain (solar diffuser degradation);
- Gain (temperature dependence);
- Gain (scan angle dependence);
- Gain (polarization dependence);
- Gain (optics degradation, wavelength dependence);
- Stray light response function (both offset & gain).
- Geolocation of observations.

1.2 High accuracy requires calibration for all these factors ON ORBIT !

- Comprehensive onboard calibration system does not exist.
- Comprehensive onboard calibration system would have very high costs $\times N_{\text{sensors}}$

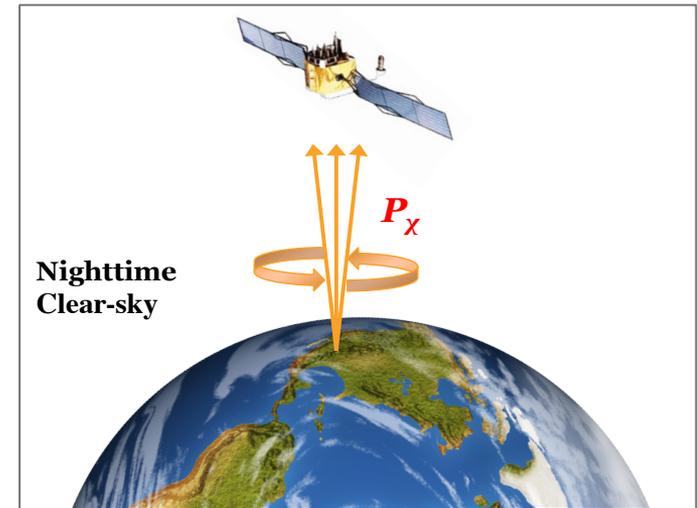
All this leads to increasing uncertainty in Earth Science data products



2. GSLC Operations & Measurements

2.1 Sensitivity to Polarization:

- Polarized laser beam transmitted to Target sensor on orbit.
- Beam polarization rotated from 0° to 360° within seconds.
- **Relative:** normalization to intensity at 0°, 180°, 360°.

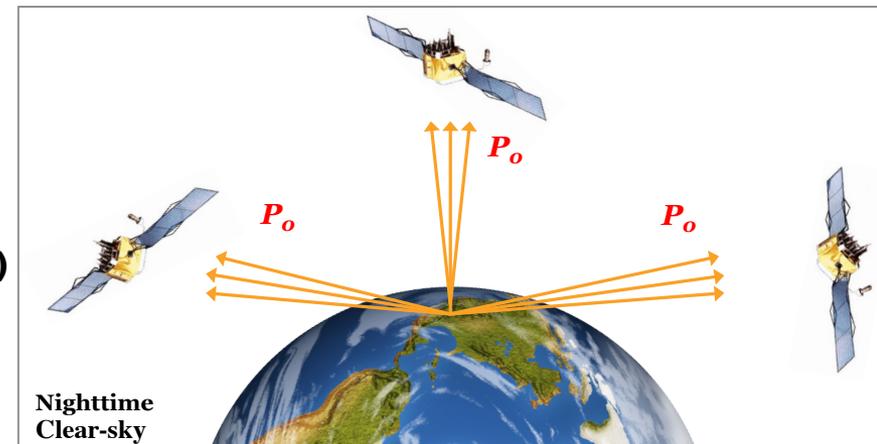


2.2 Optics Degradation:

- Non-polarized laser beam transmitted to Target sensor on orbit. Wavelengths changes from blue to red within short duration (seconds).
- **Relative:** ratio instrument response in blue to response in red (correction for atmosphere).
- Tune laser wavelength (20 – 50 nm change) within seconds (narrowband Spectral Response mapping).

2.3 Response to Stray Light:

- Target sensor in nominal mode (e.g. cross-track).
- Laser beam transmitted to Target sensor on orbit.
- **Relative:** normalize to response in direct view.
- Special operations by sensor (imaging the GSLC site) are feasible.



2.4 SC/Sensor Attitude (beacon):

- Laser beam transmitted to Target sensor on LEO/GEO orbit.
- Radiometric accuracy or polarization are not required (only good signal-to-noise ratio).

3. GSLC Heritage: SLR, SLC and Radiometric

3.1 Satellite Laser Ranging (SLR):

- Satellite tracking
- Pulsed laser (100 – 2000 Hz)
- Time-of-Flight measurements

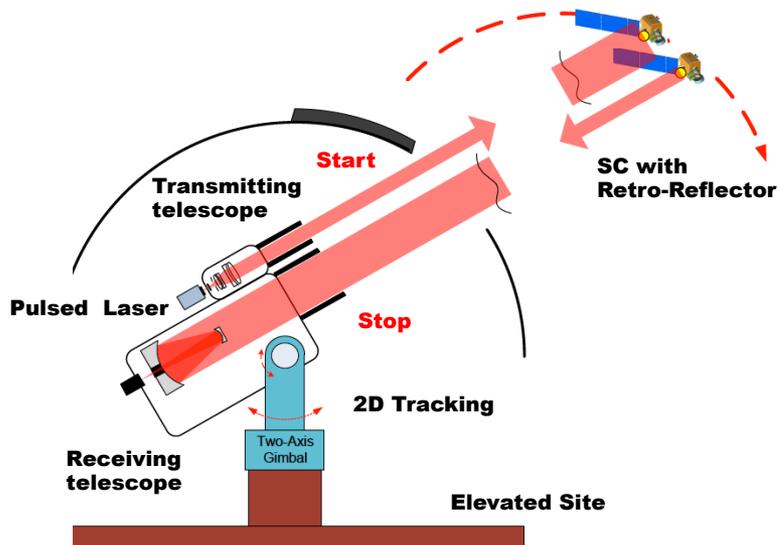


Figure: Operational SLR station

3.2 Satellite Laser Communications (SLC):

- Satellite tracking, beacon CW laser beams (4)
- Pulsed Communication Laser in MHz range

Optical data links (ongoing project, JPL):

- GEO-to-LEO
- LEO-to-Ground
- Turbulence mitigation: multiple laser beams

3.3 Initial Radiometric measurements:

Aruga et al., 1984 (Japan): LEO Satellite at 1000 km altitude. Signal detected by on-board camera (nighttime, clear-sky), **no pointing ability.**

Aruga et al., 1985 (Japan): Signal detected by GEO weather imager (nighttime, clear-sky). The imager is on a spinning S/C, **no pointing ability.**



4. GSLC Physics Concept: Radiometry & Polarization

S/C size = does NOT drive the system design !

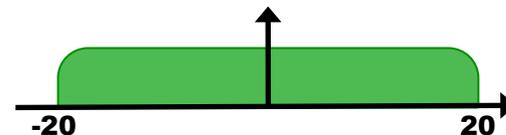
Major Driver: effects From atm. turbulence !



LEO RS Sensor:
609 km orbit.
 $t_{int} = 67 \text{ ms}$ (15 Hz)

Beam diameter = 40 m

Relative beam profile



All measurements are **RELATIVE**:

- S_S / I_T (normalization)
- S_R / I_T (stability)
- S_{blue} / S_{nir}
- S_{pol} / S_{pol} (0°, 180°, 360°)

Expanded Laser beam (7 arcsec)

Atmospheric Turbulence effect:

- Beam wandering:
 - Similar to pointing jitter > 100 Hz;
 - Similar to dynamic tracking error. Scintillation.
- Elevated site reduces atmospheric turbulence effects about 60%.

Top-of-Atmosphere

NIGHTTIME CLEAR SKY Atmosphere Transmittance > 90% (window spectral range)



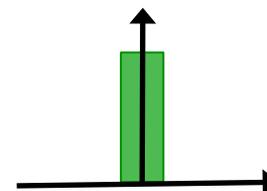
← Turbulence Layer

Atm. Turbulence:
 $C_n^2 = 10^{-13}$
 $r_o = 10 - 20 \text{ cm}$
 $t_o < 10 \text{ ms}$



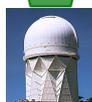
← Turbulence Layer

Beam waist = 0.5 m (CW Laser, 3 W)



Top-hat beam profile

Hosting Dome



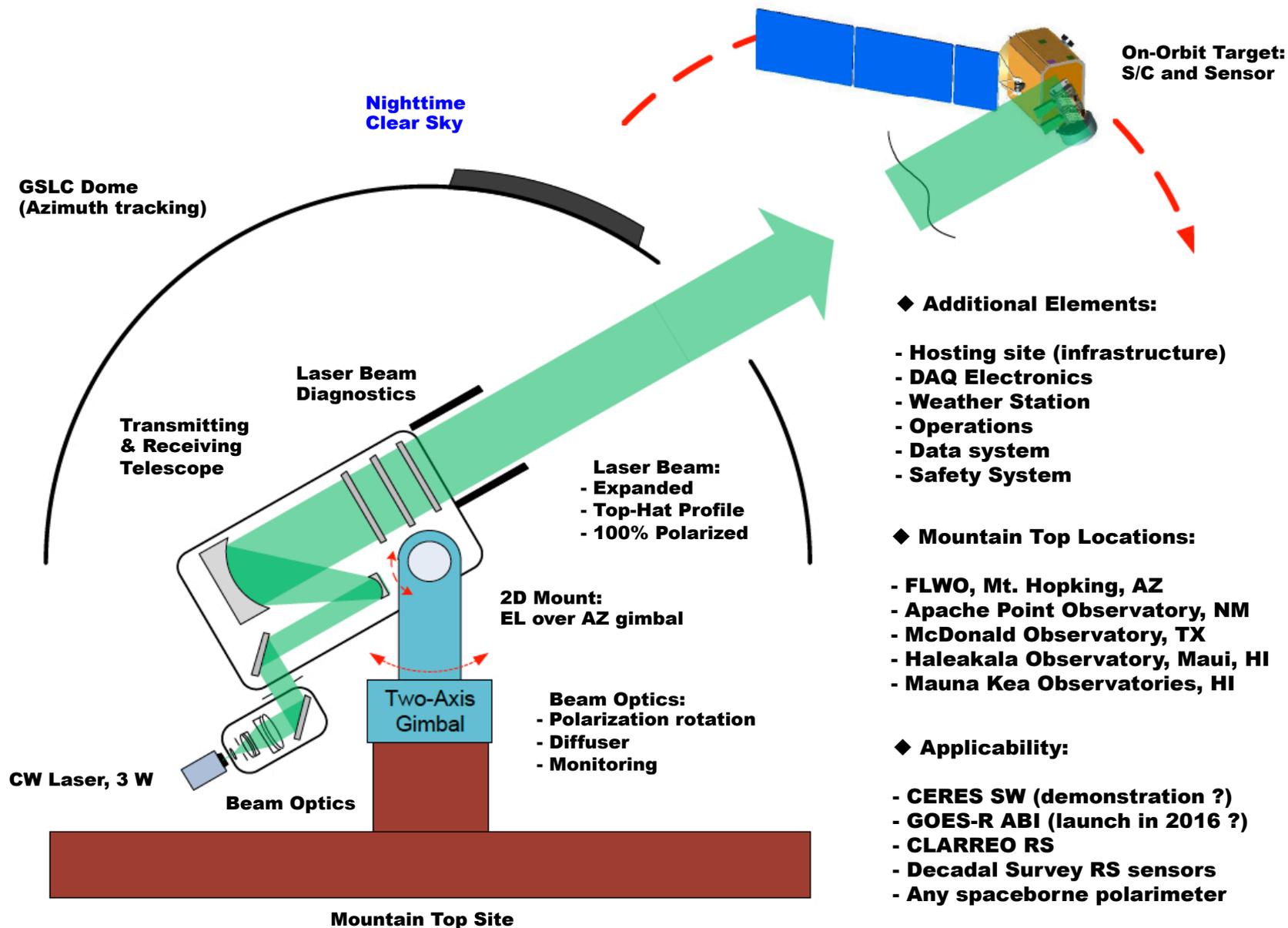
Mt. Hopkins, AZ. Altitude = 2,617 m

Seeing Index = 0.6 arcsec

Sea level, altitude = 0 m



5. GSLC Elements:



5.1 GSLC Elements: Common Elements with SLR / SLC

5.1.1 Tracking Requirements

- **2D Elevation over Azimuth gimbal.**
- **Slew rates: no less than 20° s^{-1} (EL) and $> 30^\circ \text{ s}^{-1}$ (AZ).**
- **Acceleration: no less than 5° s^{-2} (EL) and $> 5^\circ \text{ s}^{-2}$ (AZ).**
- **Dynamic Tracking Error: RMS < 1 arcsec.**
- **Total Beam Deviation: +/- 6 arcsec (characterized).**

5.1.2 Ground Systems

- **Hosting Dome with Azimuth tracking.**
- **Auxiliary Weather station (e.g. 5 sensors).**
- **Recording all monitoring data (laser, beam, weather, etc.)**

5.1.3 Data Storage

- **Data volume in Gb range (small).**
- **Data storage and data system: small size.**
- **CLARREO SCF (funded) is sufficient.**

5.1.4 Operations

- **Predicting calibration opportunities using most recent TLE (ephemeris).**
- **Satellite tracking.**



5.2 GSLC Elements: Specific Elements

5.2.1 Tunable CW Laser

- **CW (or quasi-CW) laser for high stability.**
- **Power: 3 W is sufficient for most applications.**
- **Operation at different wavelengths (fixed).**
- **Wavelength tuning (dynamic).**

5.2.2 Laser Beam Profile and Monitor

- **Uniform expanded laser beam with top-hat profile (to mitigate beam wandering)**
- **Off-axis Transmit Telescope to avoid beam obscuration.**
- **Reduce effect of beam scintillation (see Slide 13).**

5.2.3 Polarization Control and Monitor

- **Polarization is not changed by the clear atmosphere !**
- **Polarization rotation optics and monitor is required.**

5.2.4 Accurate Intensity Monitor

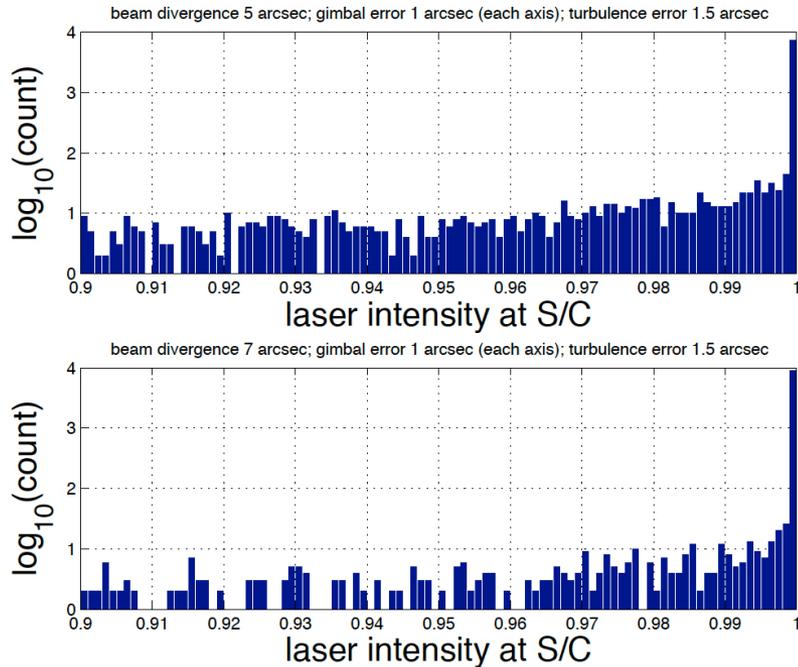
- **Frequent recording of outgoing beam intensity, to be used for normalization.**

5.2.5 Operations

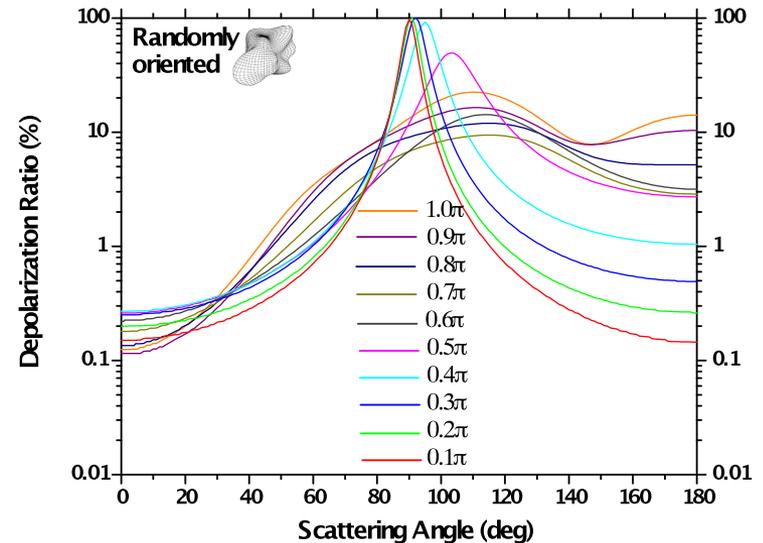
- **Special Operations by Target Sensor: staring/pointing at the GSLC site.**



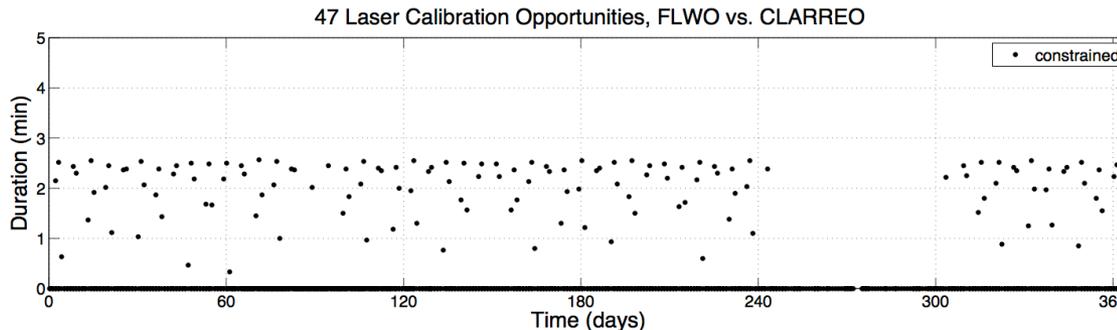
5.3 GSLC Elements: modeling



↑ Simulation of beam relative intensity on orbit: in both cases we used top-hat beam profile with ideal uniformity and Gaussian tails of $\sigma = 2$ arcsec, tacking error contribution 1 arcsec (each gimbal axis), and error due beam wondering 1.5 arcsec. Plots show distribution of relative beam intensity with beam divergence of 5 arcsec (top), and 7 arcsec (bottom).



↑ RT calculations: depolarization ratio at 532 nm as function of scattering angle for Gaussian-shaped aerosol particles of different size. Depolarization in forward scattering direction (laser beam) is below 0.3%.



← Time duration of 47 calibration opportunities for CLARREO RS (90°P orbit, 609 km altitude) and GSLC (FLWO location, Mt. Hopkins). Constrain in EL is 45°, in SZA > 105°, slew rates and acceleration limits.



6. Required Technology Development

6.1 Expanded Beam Top-Hat Profile (to reduce beam wandering)

- **Current diffusers: RMS = 5% uniformity. Goal → RMS = 1%.**

6.2 Laser Beam Polarization (uniform polarization > 99%)

- **Optics optimization to have uniform polarization across the beam profile.**

6.3 Reduction of Scintillation (Steve Brown, NIST)

- **Laser system concept for reducing scintillation due to atmospheric turbulence.**

7. Roadmap Forward

7.1 Publication of the concept & recommendations for implementation.

7.2 Possibility: next ESTO IIP Announcement of Opportunity, Spring 2013. Collaboration of LaRC, NIST, LASP, and UNM groups:

- **LaRC: RT and orbital modeling, S/C tracking, demonstration with CERES SW (?)**
- **NIST: Laser system and optics, beam diagnostics, profile, and polarization.**
- **LASP: Demonstration with instrument prototype for CLARREO RS.**
- **UNM: Atmospheric corrections, hosting site logistics, operations.**

